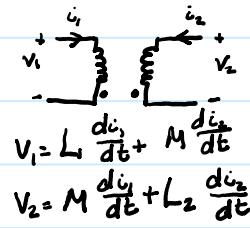
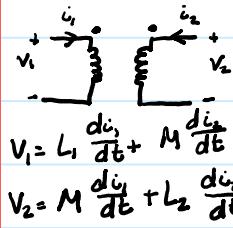
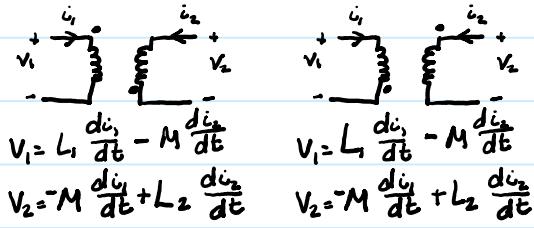


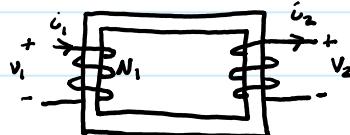
Last time: Dot Convention



* Dot location doesn't effect self inductance term voltage drop.



Ideal transformer:



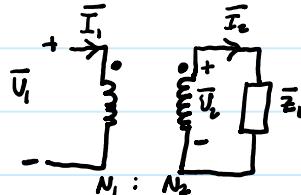
$$\frac{V_1}{V_2} = \frac{N_1}{N_2} = a$$

$$\frac{i_1}{i_2} = \frac{N_2}{N_1} = \frac{1}{a}$$

$$P_1 = P_2$$

- Today:
- 1) Ideal transformer and impedances
 - 2) Max power transfer
 - 3) Equivalent circuit for transformer

Impedances and Transformers:



$$\bar{V}_2 = \bar{Z}_L \bar{I}_2$$

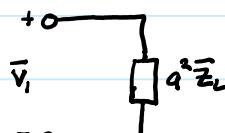
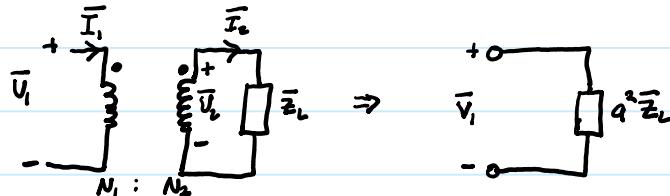
$$\bar{V}_1 = a \bar{V}_2$$

$$\bar{V}_1 = a \bar{Z}_L \bar{I}_2$$

$$\bar{I}_1 = \frac{1}{a} \bar{I}_2 \Rightarrow \bar{I}_2 = a \bar{I}_1$$

$$\bar{V}_1 = a^2 \bar{Z}_L \bar{I}_1$$

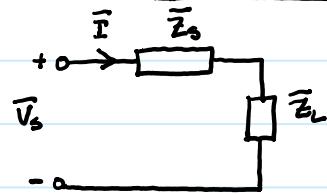
$$\boxed{\bar{V}_1 = (a^2 \bar{Z}_L) \bar{I}_1}$$



* Impedance on 2 side can be moved to 1 side by multiplying by a^2 .

2018-09-26-2

Maximum power transferred to the load



$$\bar{Z}_s = R_s + jX_s$$

$$\bar{Z}_L = R_L + jX_L$$

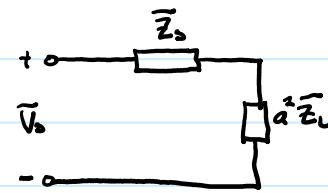
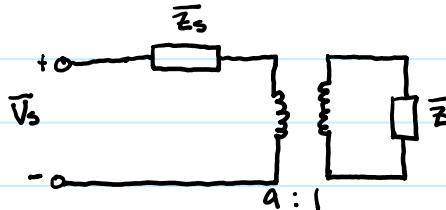
$$P_L = |\bar{I}|^2 R_L$$

$$\bar{I} = \frac{\bar{V}_s}{\bar{Z}_s + \bar{Z}_L} \Rightarrow \bar{I} = \frac{\bar{V}_s}{(R_s + R_L) + j(X_s + X_L)}$$

$$P_L = \frac{|\bar{V}_s|^2 R_L}{(R_s + R_L)^2 + (X_s + X_L)^2}$$

* Can show that for max P_L , $\bar{Z}_L = \bar{Z}_s^*$ or $|\bar{Z}_L| = |\bar{Z}_s|$ (for $\frac{R_L}{X_L}$ fixed as a constant)

* Imposing $|\bar{Z}_L| = |\bar{Z}_s|$ can easily be done by using a transformer

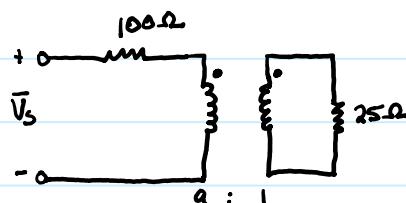


$$|a^2 \bar{Z}_L| = |\bar{Z}_s| \Rightarrow a^2 |\bar{Z}_L| = |\bar{Z}_s|$$

$$a^2 = \frac{|\bar{Z}_s|}{|\bar{Z}_L|} \Rightarrow$$

$$a = \sqrt{\frac{|\bar{Z}_s|}{|\bar{Z}_L|}}$$

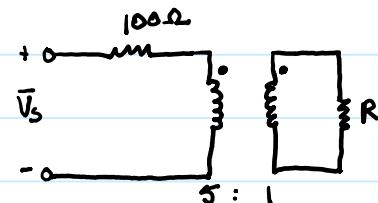
Ex



Find: a for max power transfer

$$a = \sqrt{\frac{100}{25}} = a = \sqrt{4} \Rightarrow a = 2$$

Ex

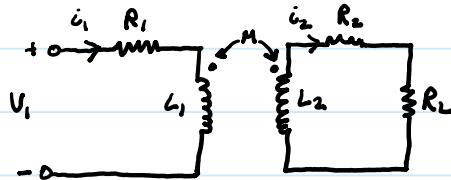


Find: R for max power transfer

$$5^2 R = 100 \Rightarrow 25R = 100 \Omega$$

$$R = 4 \Omega$$

Equivalent circuits for transformers



$$V_1 = i_1 R_1 + L_1 \frac{di_1}{dt} - M \frac{di_2}{dt}$$

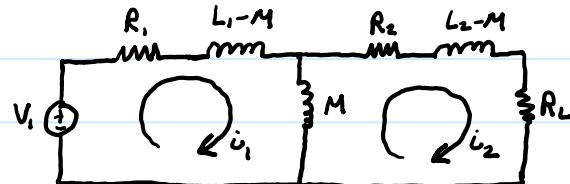
$$0 = i_2 R_2 + L_2 \frac{di_2}{dt} - M \frac{di_1}{dt}$$

* i_1 : dot \rightarrow no dot. Coil 2: current into dot $= -i_2$

* i_2 : no dot \rightarrow dot. Coil 1: current into no dot $= -i_1$

$$\Rightarrow V_1 = i_1 R_1 + (L_1 - M) \frac{di_1}{dt} + M \frac{di_2}{dt} (i_1 - i_2)$$

$$\Rightarrow 0 = i_2 R_2 + (L_2 - M) \frac{di_2}{dt} + M \frac{di_1}{dt} (i_2 - i_1) + i_2 R_L$$



* if $L_1 - M$ or $L_2 - M$ are less than 0, then the above equation shouldn't be used.

* More generally:

$$V_1 = i_1 R_1 + L_1 \frac{di_1}{dt} - M \frac{di_2}{dt}$$

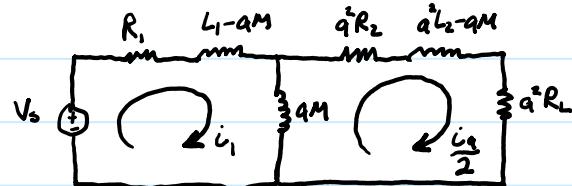
$$\Rightarrow V_1 = i_1 R_1 + L_1 \frac{di_1}{dt} - aM \frac{d(i_2/a)}{dt}$$

$$0 = i_2 R_2 + L_2 \frac{di_2}{dt} - M \frac{di_1}{dt}$$

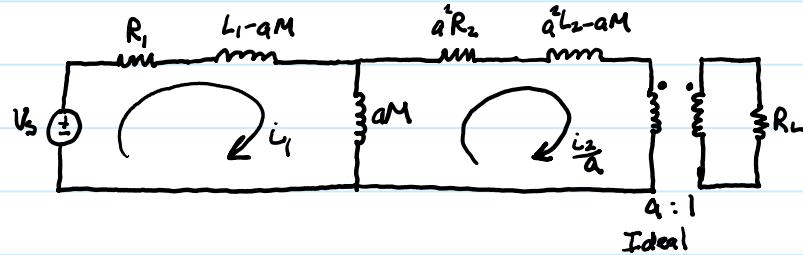
$$0 = a(i_2/a) R_2 + a(L_2 - aM) \frac{d(i_2/a)}{dt} + aL_2 \frac{d(i_2/a)}{dt} - M \frac{di_1}{dt}$$

$$\Rightarrow V_1 = i_1 R_1 + (L_1 - aM) \frac{di_1}{dt} + aM \frac{d}{dt} (i_1 - \frac{i_2}{a})$$

$$0 = a^2(i_2/a) R_2 + (a^2 L_2 - aM) \frac{d(i_2/a)}{dt} + aM(\frac{i_2}{a} - i_1) + a^2(i_2/a) R_L$$



Thevenin Equivalent



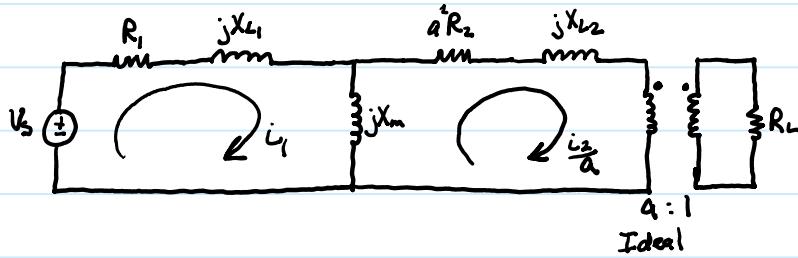
2018-09-26-4

Analysis for sinusoidal steady state

$$\bar{V}_i = V_m \cos(\omega t + \phi)$$

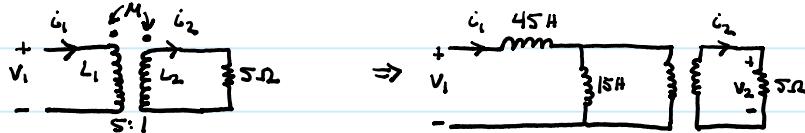
Steps: 1) Convert all inductances to reactances

$$X_L = \omega L$$



2) Solve the circuit using phasors.

Ex | Problem 3.12



$$aM = 15H \Rightarrow M = 3H$$

$$L_1 - aM = 45H \Rightarrow L_1 = 60H$$

$$a^2 L_2 - aM = 0 \Rightarrow L_2 = \frac{M}{a} \Rightarrow L_2 = \frac{3}{3} = 0.6H$$

$$k = \frac{M}{\sqrt{L_1 L_2}} \Rightarrow k = 0.5$$